

# **Panel on "Intelligent Automation and Autonomy for a safe and secure Air Transport System."**

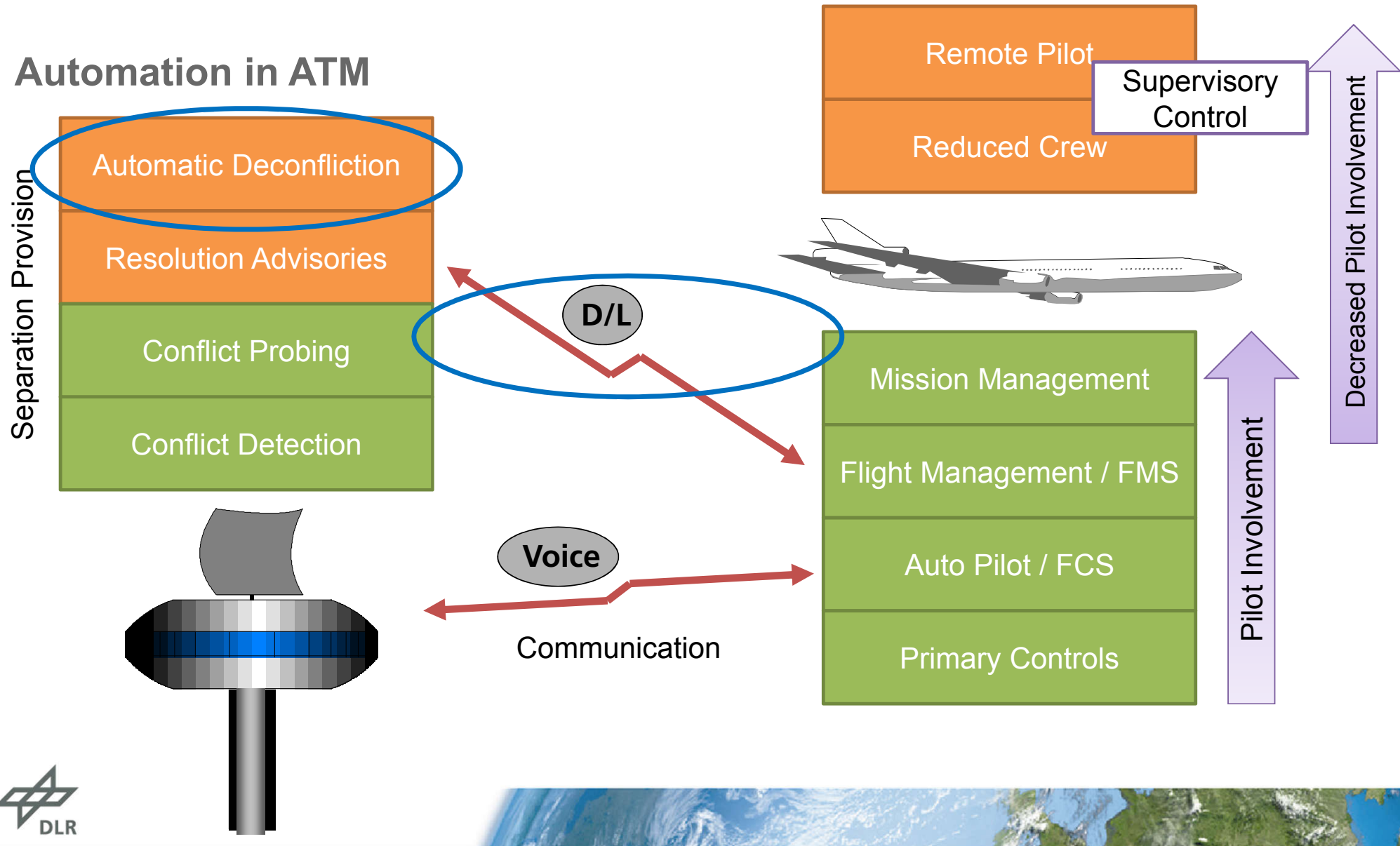
## **Concepts on how to introduce higher level of Automation in ATM**

Dr. Bernd Korn  
DLR – Institute of Flight Guidance

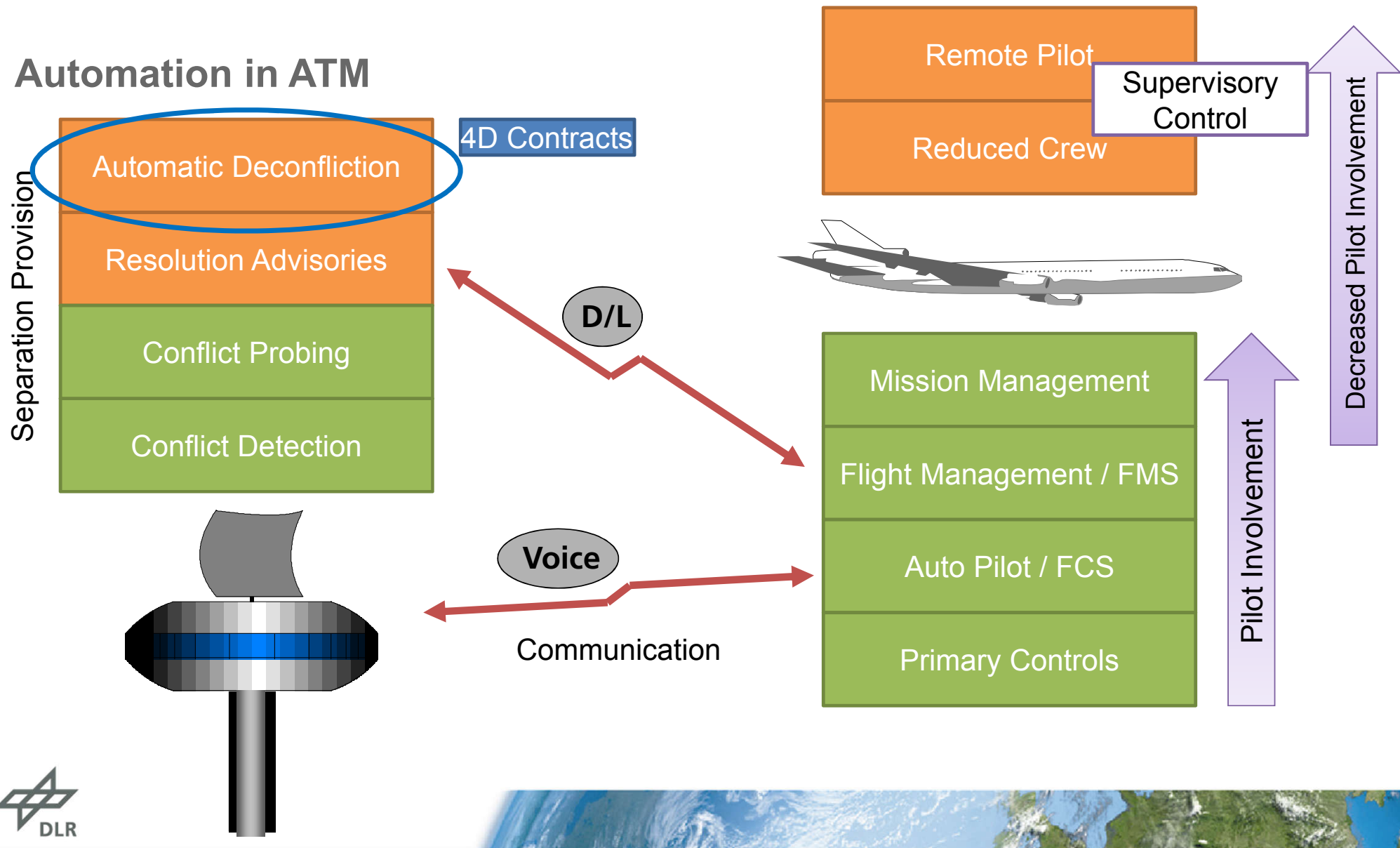
A large, curved image of the Earth from space occupies the bottom right portion of the slide. It shows a view of the planet's surface, including clouds, oceans, and landmasses. The curvature of the Earth is prominent, with the horizon line visible. The colors are vibrant, with deep blues for the oceans and bright whites for the clouds.

Knowledge for Tomorrow

## Automation in ATM



## Automation in ATM

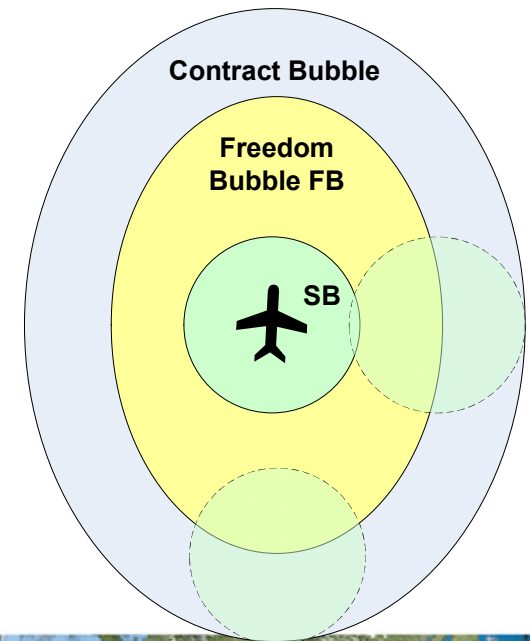
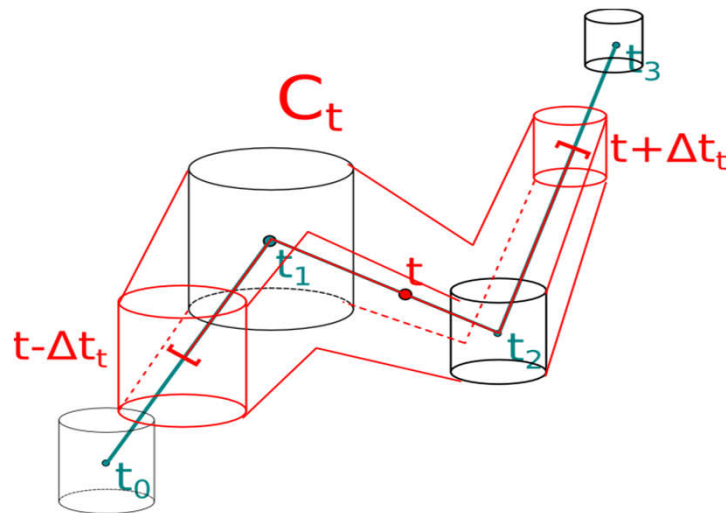
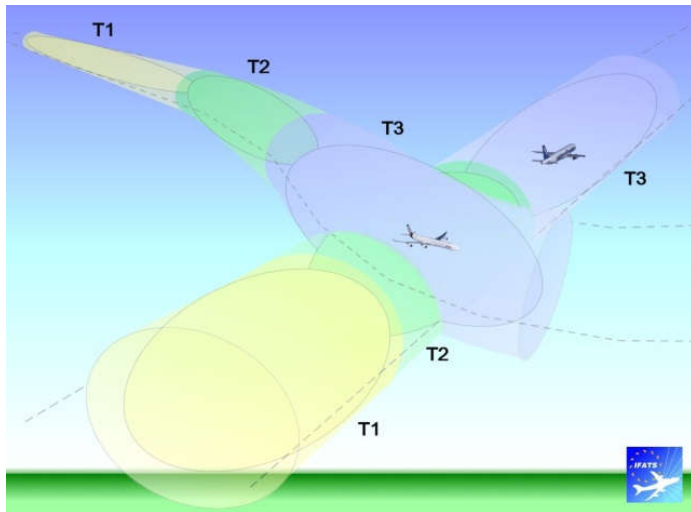


## Separation Provision by Shared Responsibilities Contract Based Control

Conflict free Contracts are assigned to A/C

A/C is responsible to stay within the contract

ATC monitors – is only active if contract is violated



## Contract Definition

Trajectory bone

Safety Bubble

- Margins around the aircraft
- At any time, 2 SB must not intersect

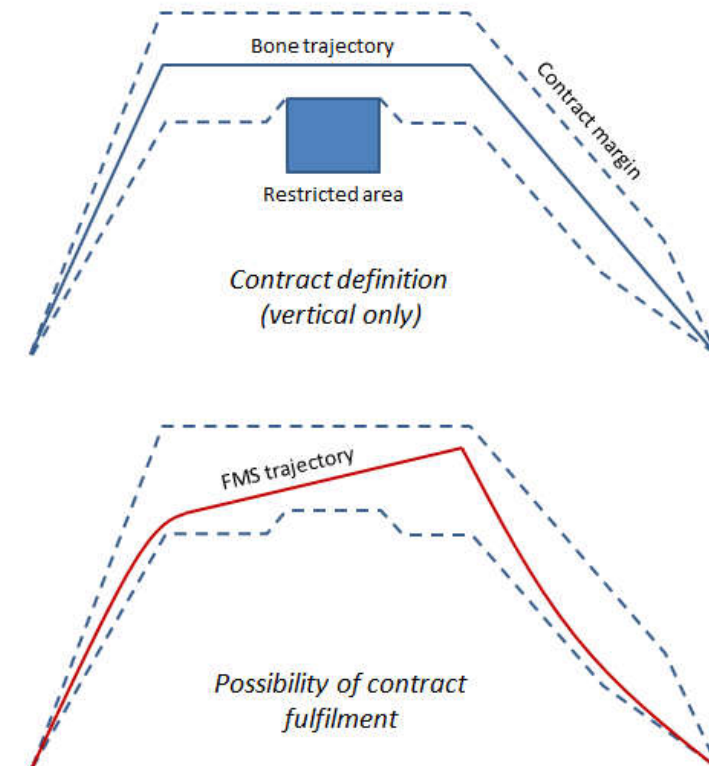
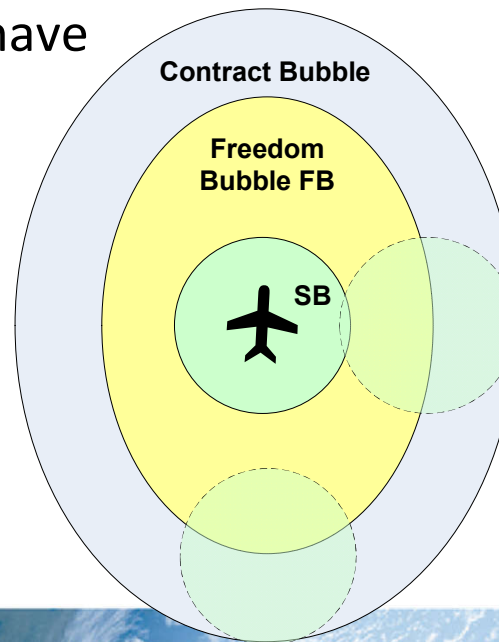
Contract Bubble:

- Calculated by the ground to have conflict-free 4D contracts
- At any time, 2 CB should not intersect

Freedom Bubble

- Calculated by the FMS from CB and SB

4D contract = Bone + SB + CB





## 4D – Contracts: Simulations

### 4 Scenarios

#### Benelux - airspace

- Benelux 100% = 5297 flights
- Benelux 233% = 11925 flights

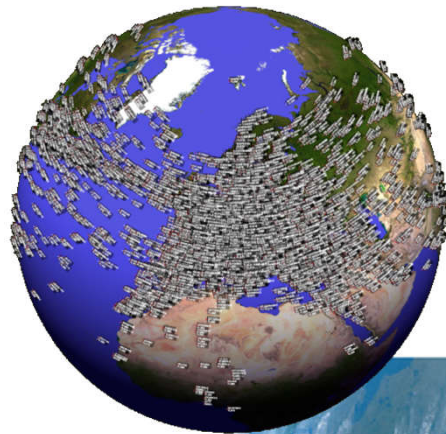
#### Separations:

6.0 NM/1000 ft above and in FL100

3.2 NM/1000 ft below FL100

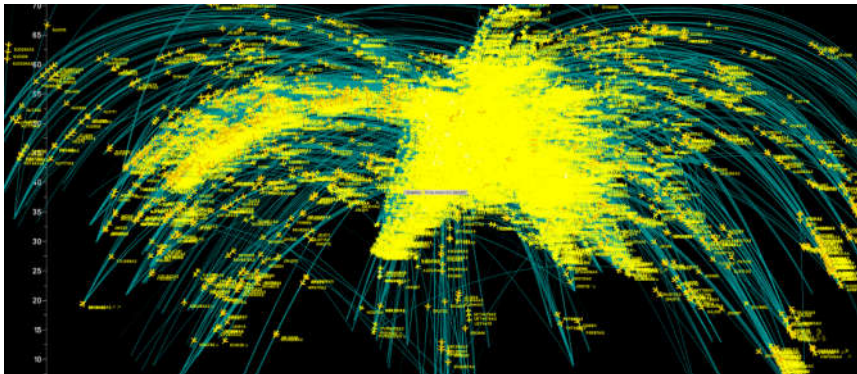
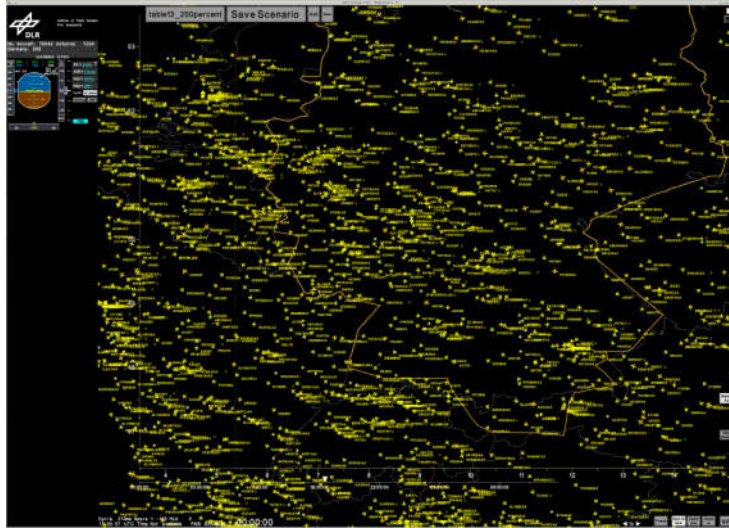
3.0 NM safety

ECAC 233%



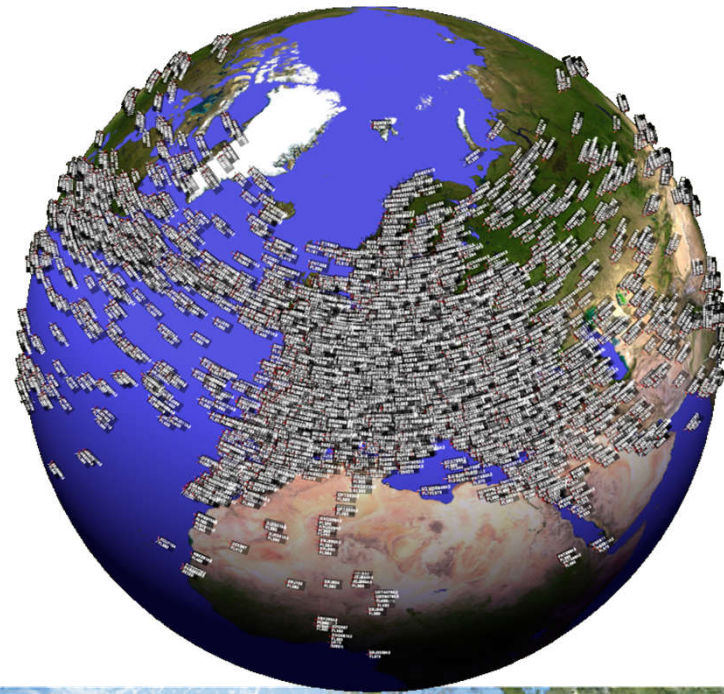
Scenario	Traffic	Event
S1	100% Benelux Traffic	~5 kts wind deviation between forecast and actual
S2	233% Benelux Traffic	~5 kts wind deviation between forecast and actual
S3	100% Benelux Traffic	Airport closure Luxembourg, replan to Brussels airport
S4	100% Benelux Traffic	Decompression, immediate decent, generating a conflict with another aircraft

# TrafficSimulation



## DLR's TrafficSim

- Simulates a large number of AFMS-equipped (and unequipped) aircraft
- Supports scenarios with more than 100.000 aircraft in realtime



## Analysis (100% Traffic)

Scenario		Original	4DCoGC	Relative
Number of Flights		5297	5297	N/A
Heavy		876	876	16,5%
Medium		4209	4209	79,5%
Small		212	212	4,0%
Number of Conflicts		3170	3487-->0	0,0%
Number of Trajectory Points	$\mu \pm \sigma$	31.1 $\pm$ 16.9	139.6 $\pm$ 99	448,9%
	[min,max]	[3,94]	[19,666]	
Distance [NM]	$\mu \pm \sigma$	1194 $\pm$ 1275	1155 $\pm$ 1249	96,7%
	[min,max]	[17,5880]	[25,5917]	
Duration [s]	$\mu \pm \sigma$	10121 $\pm$ 9390	9837 $\pm$ 9417	97,2%
	[min,max]	[406,51174]	[529,45733]	
Beeline from Departure to Arrival [NM]	$\mu \pm \sigma$	1139 $\pm$ 1250		N/A
	[min,max]	[17,5880]		





## Analysis (233% Traffic)

Scenario		Original	4DCoGC	Relative
Number of Flights		11925	11925	N/A
Heavy		2073	2073	17,4%
Medium		9225	9225	77,4%
Small		627	627	5,3%
Number of Conflicts		20303	17882-->0	0,0%
Number of Trajectory Points	$\mu \pm \sigma$	31.6 $\pm$ 17	142.2 $\pm$ 99.6	450,0%
	[min,max]	[3,90]	[19,666]	
Distance [NM]	$\mu \pm \sigma$	1229 $\pm$ 1291	1189 $\pm$ 1264	96,7%
	[min,max]	[23,6089]	[25,5917]	
Duration [s]	$\mu \pm \sigma$	10398 $\pm$ 9520	10112 $\pm$ 9514	97,3%
	[min,max]	[406,51174]	[529,45733]	
Beeline from Departure to Arrival [NM]	$\mu \pm \sigma$	1174 $\pm$ 1265		N/A
	[min,max]	[17,5880]		

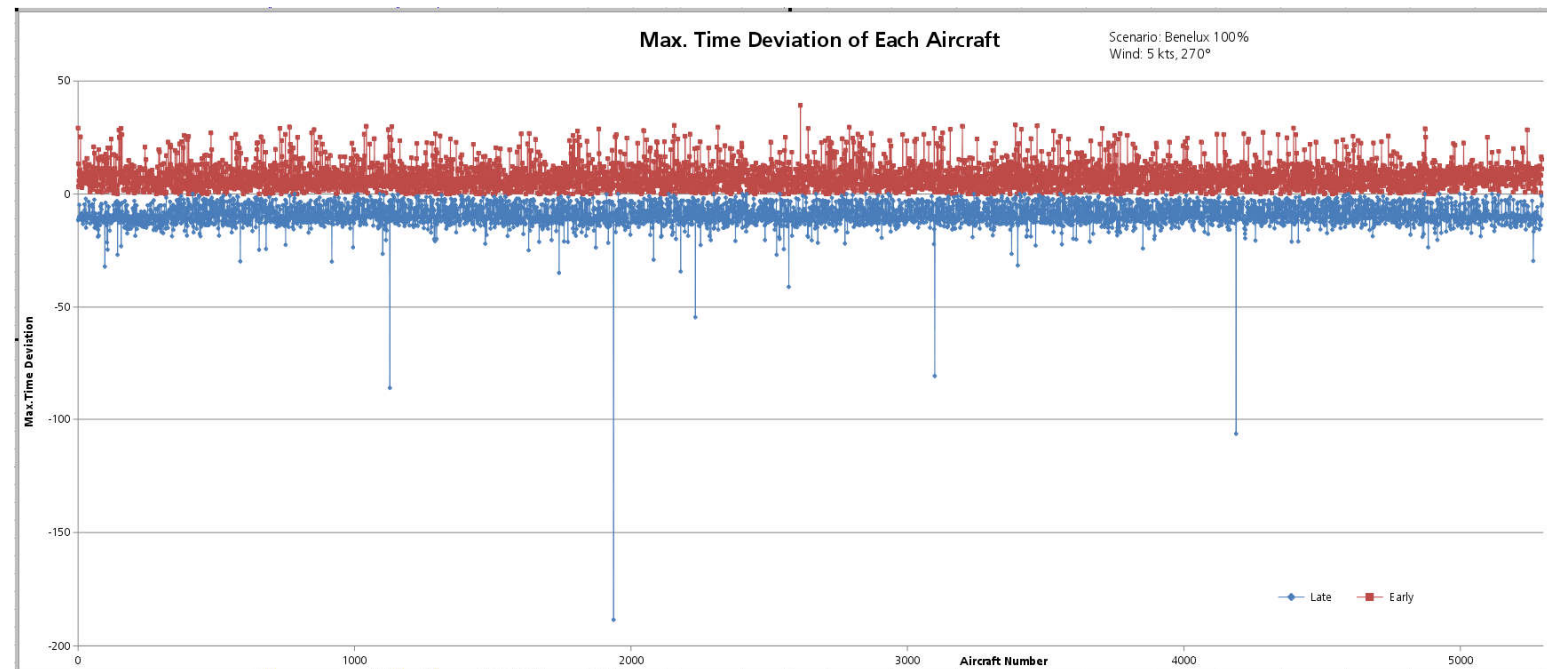


## Analysis: Compliance to Contract

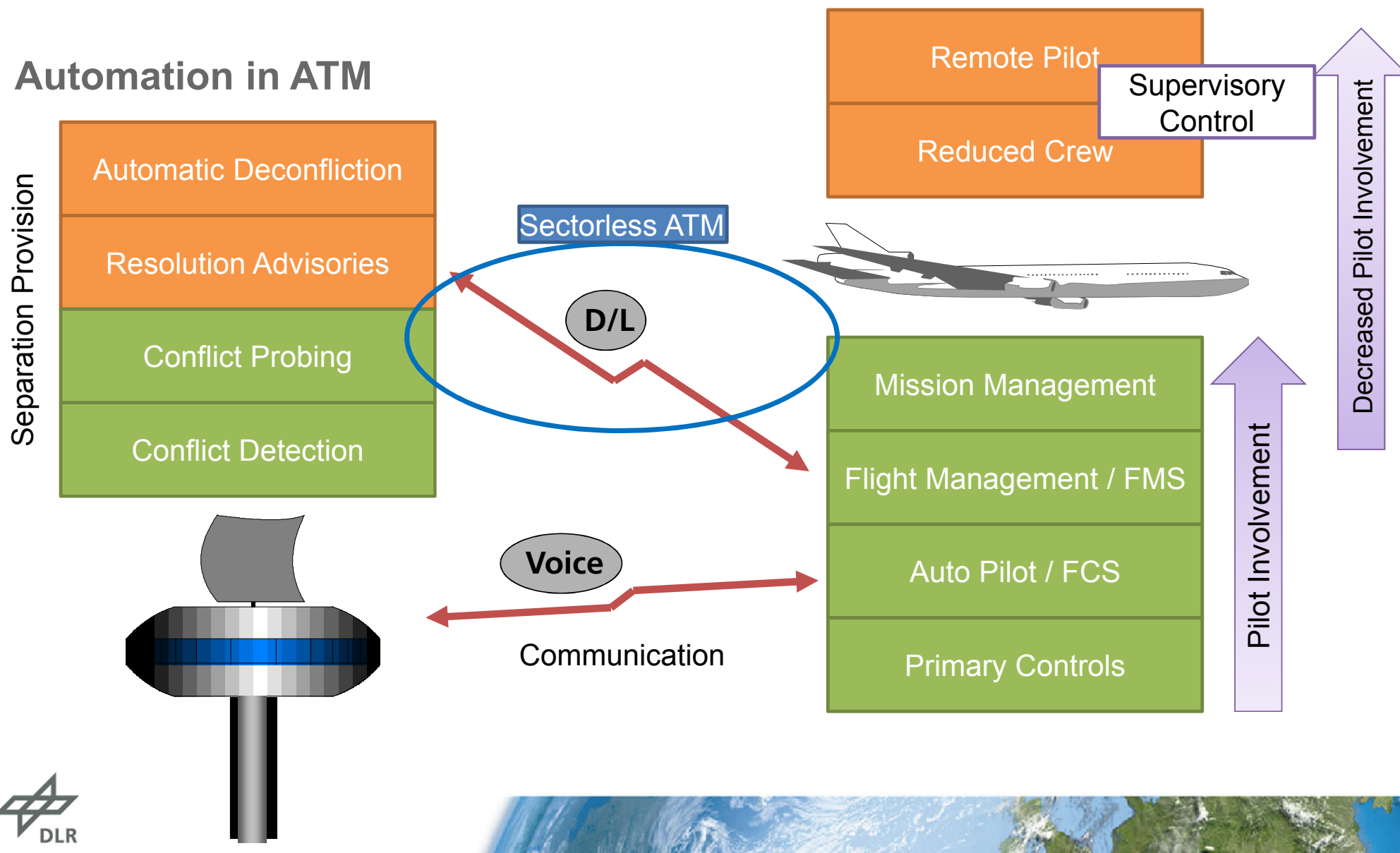
100% Traffic -> 99.66% fulfilled initial contract

233% Traffic -> 98.99% fulfilled initial contract

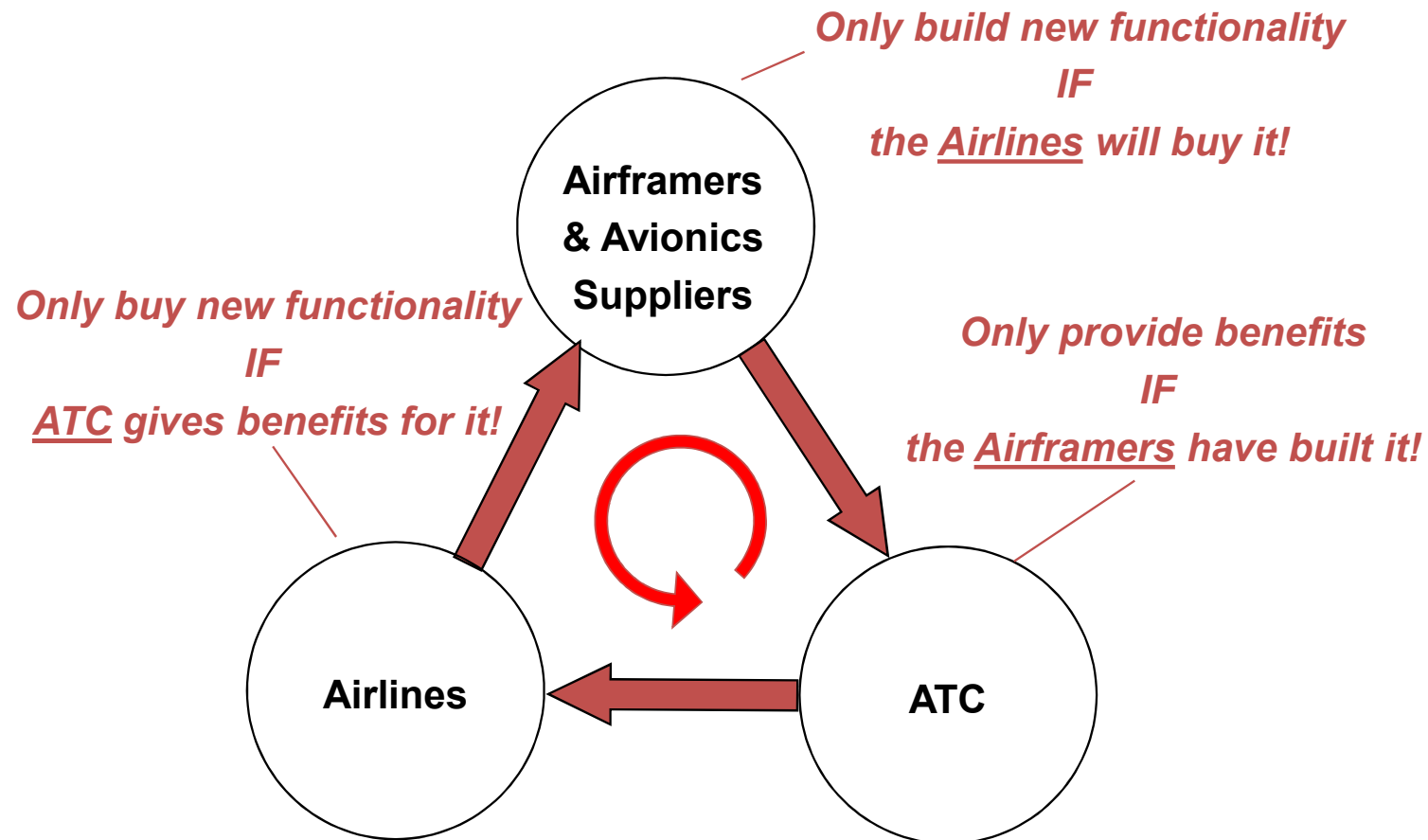
Regenerate reason: wind mismatch of ~5 kts



## Automation in ATM



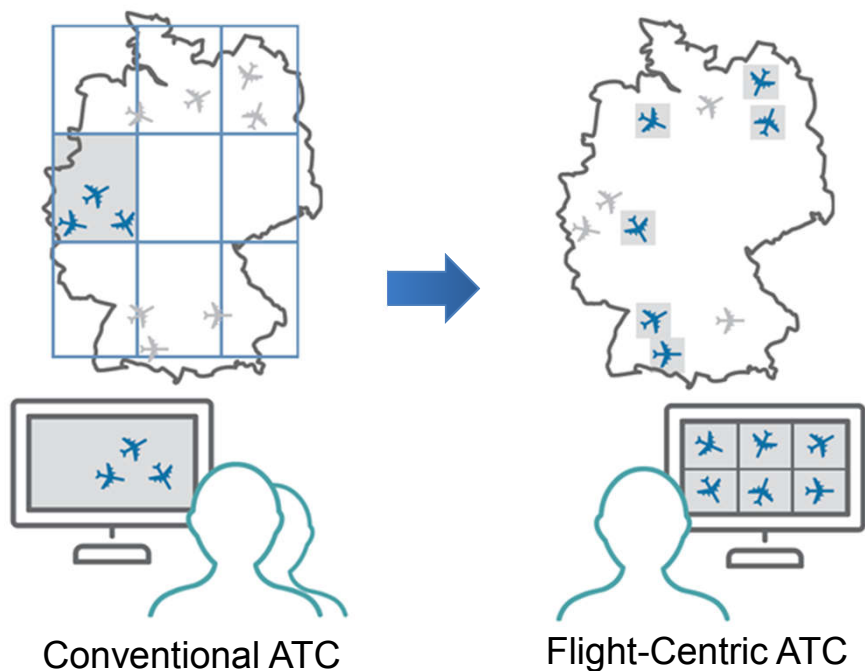
## Automation in ATM: The Problem of Mixed Equippage



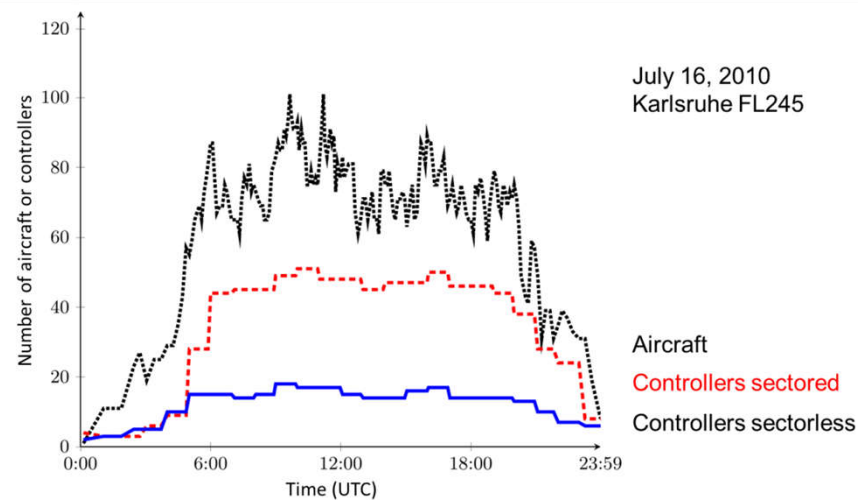
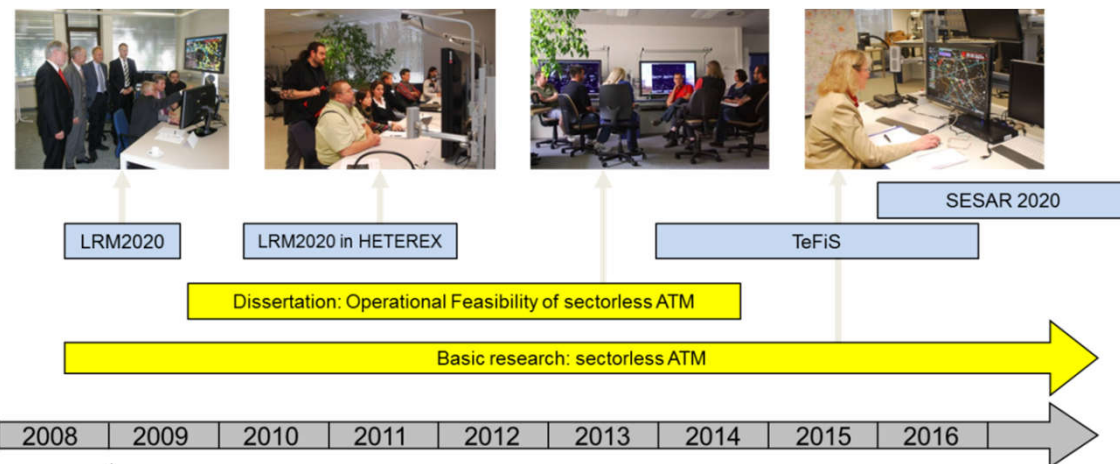


# Sectorless Air Traffic Management (flight-centric ATC)

## Robust and Efficient En-route Operations



DFS Karlsruhe (UAC) 2021



# Sectorless ATM – Important Concept Components

Flight Phase	Priority
Level, Level	Right Aircraft
Overtaking Criteria = false	
Level, Level	Slower Aircraft
Overtaking Criteria = true	
Level, Level but close to TOD	Aircraft in Level
Climb, Level	Aircraft in Level
Descent, Level	Aircraft in Level
Climb, Descent	Aircraft in Descent
Climb, Climb	Lower Aircraft
Descent, Descent	Upper Aircraft
Emergency	Aircraft in Emergency State
Efficiency	Aircraft with less Avoidance Manoeuvre

Flight Rules



Controller WP



CD&R

FL380 0.76 mach 350 deg  
 RYR3623 << turning right heading select 336 deg  
 controller >> RYR3623 descend to flight 360  
 RYR3623 << descend to flight 360  
 controller >> RYR3623 perform direct to intend  
 RYR3623 << direct to intend

Datalink



Voice  
Communication



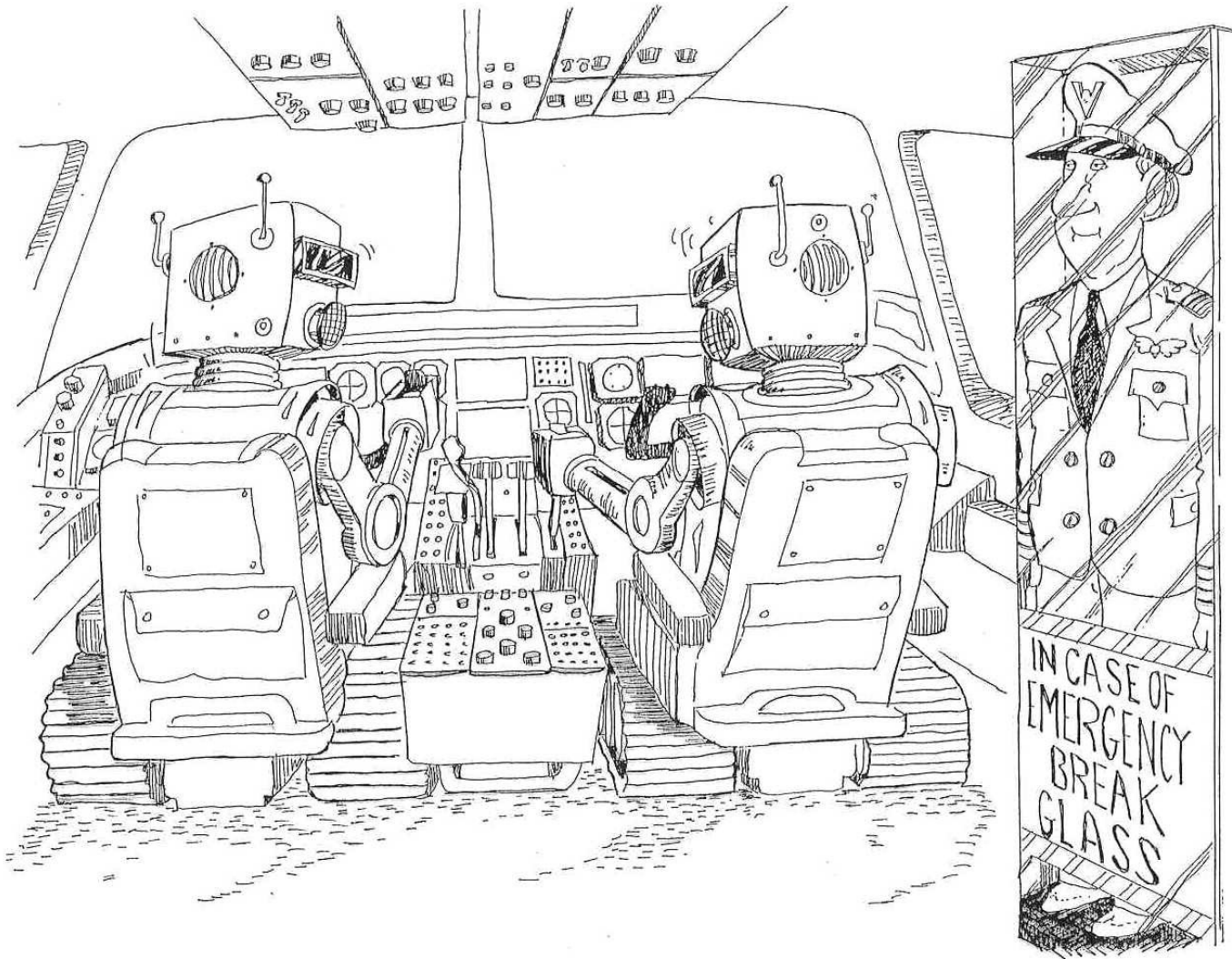
Assignment Center



# Sectorless ATM – HMI concept (here Tiled Display)



## Questions?





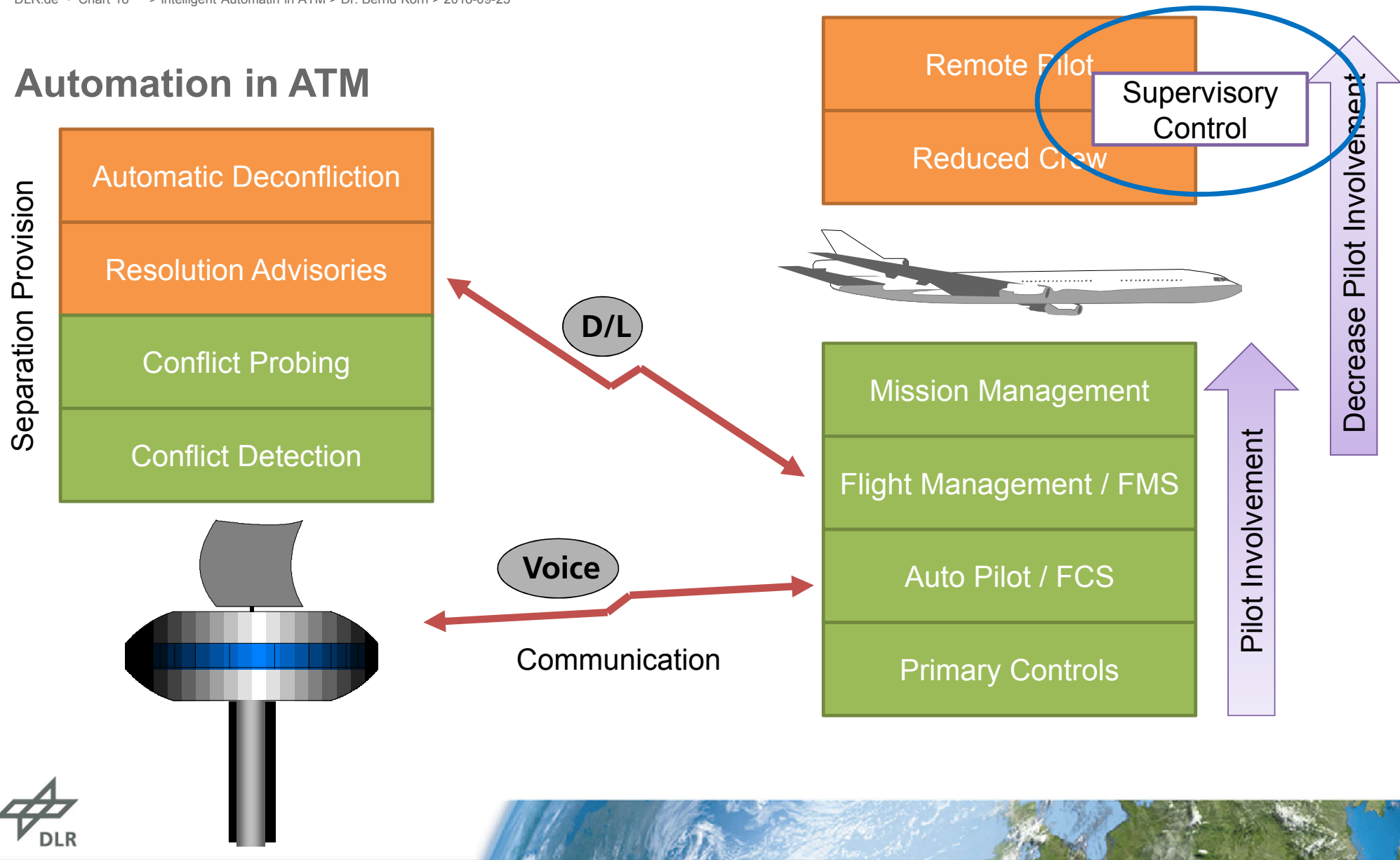
## Backup Slides



Knowledge for Tomorrow



## Automation in ATM



## Supervisory Control: Information

**1 aircraft**



# Supervisory Control: Information

1 aircraft



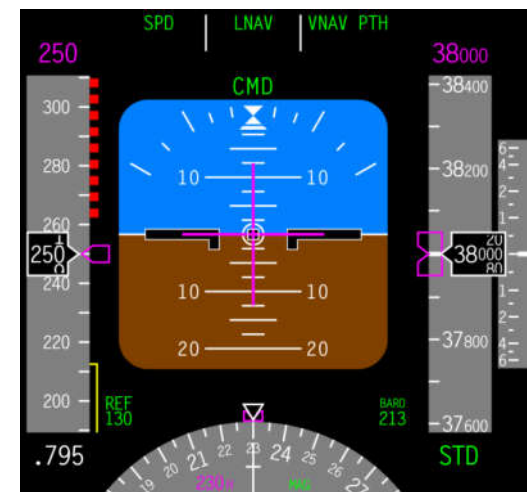
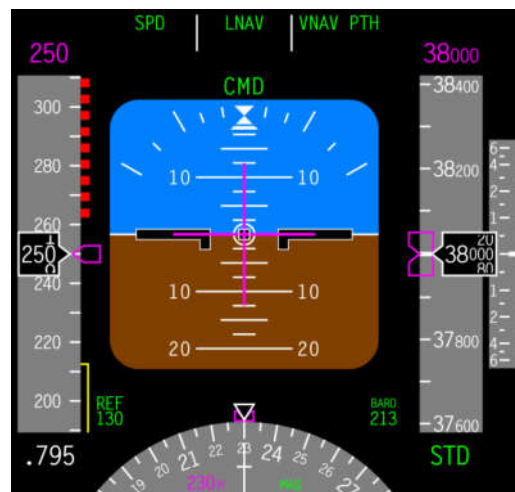
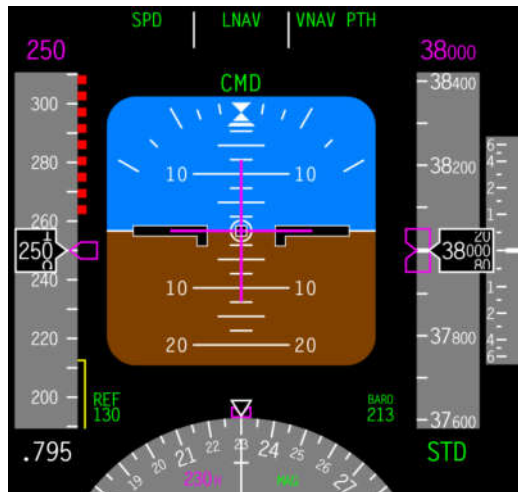
*Everthing ok?*





# Supervisory Control: Information

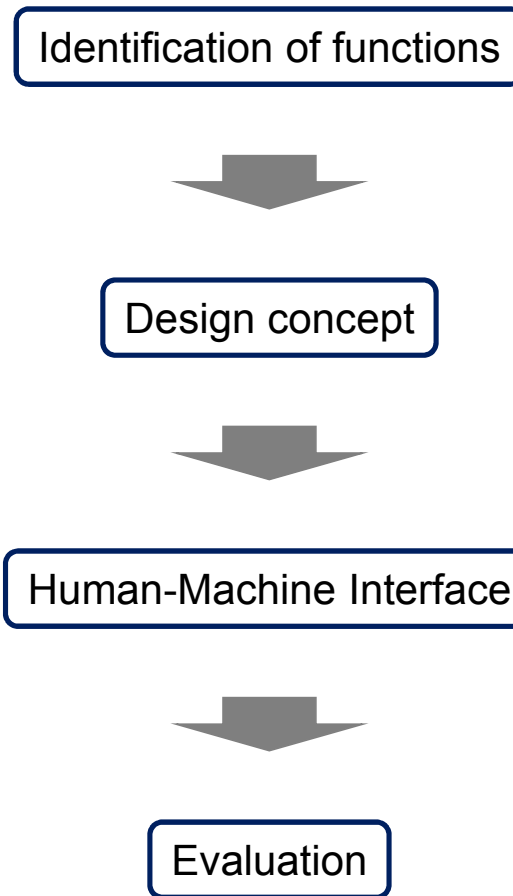
3 aircraft



*Everthing ok?*



# Supervisory Control: HMI Design Process



# Identification of Functions

## Abstraction Hierarchy

### Functional Purposes

Reasons and purposes why the work system exists.

### Abstract Function

Criteria by which the achievement of purposes can be judged.

### Generalized Function

Functions that are necessary to achieve the purpose of the work system.

### Physical Function

Physical processes that are necessary for execution of the generalized functions.

### Physical Form

The actual physical objects of the work system.

WHY



WHAT

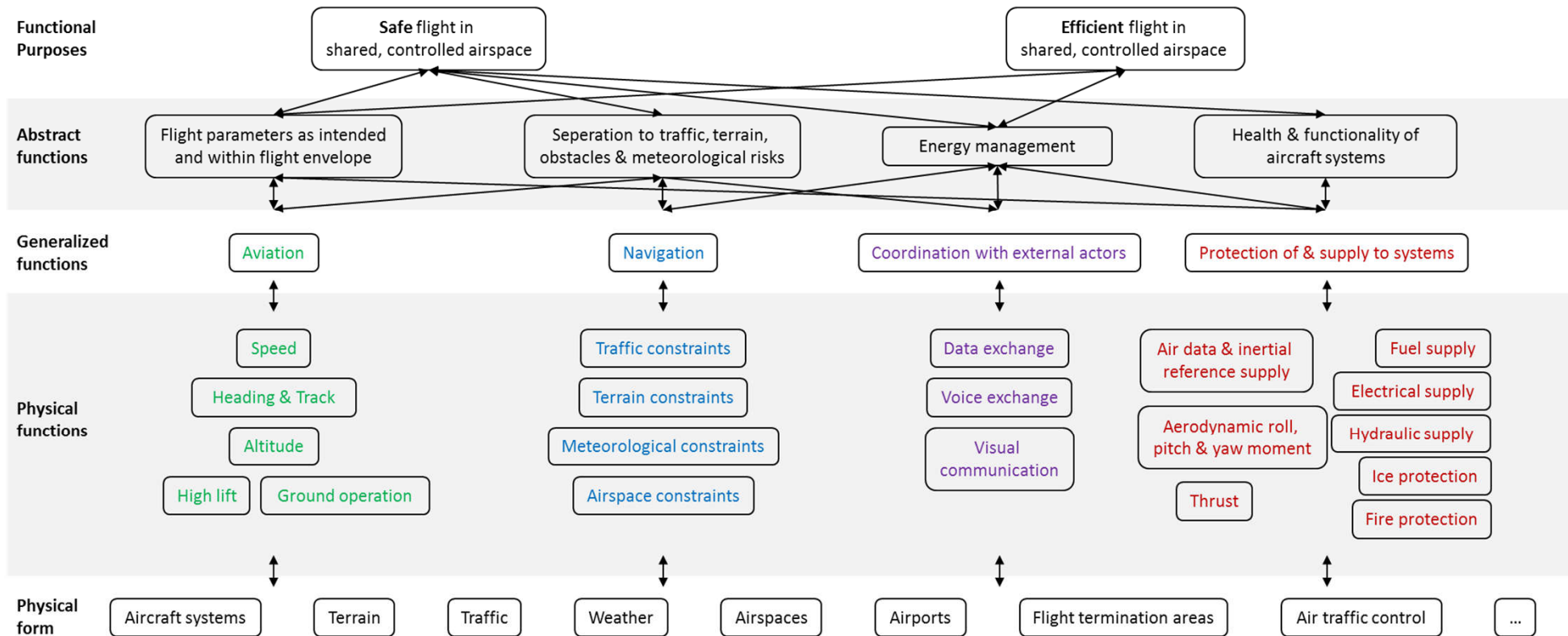


HOW



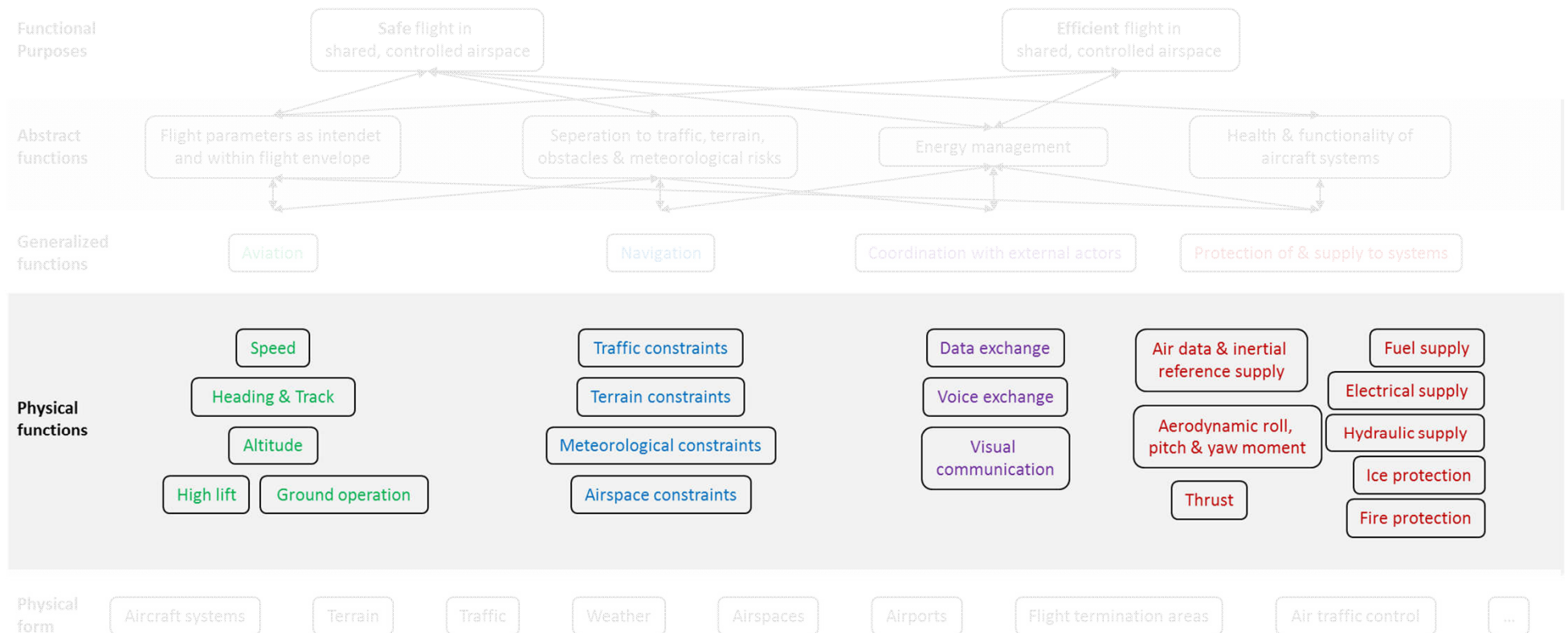
# Identification of Functions

## Abstraction Hierarchy

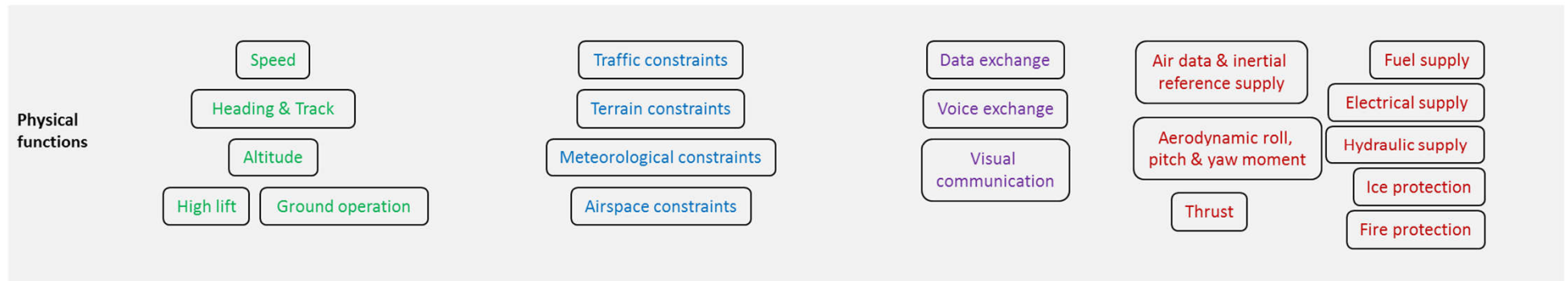




# Design Concept



# Design Concept



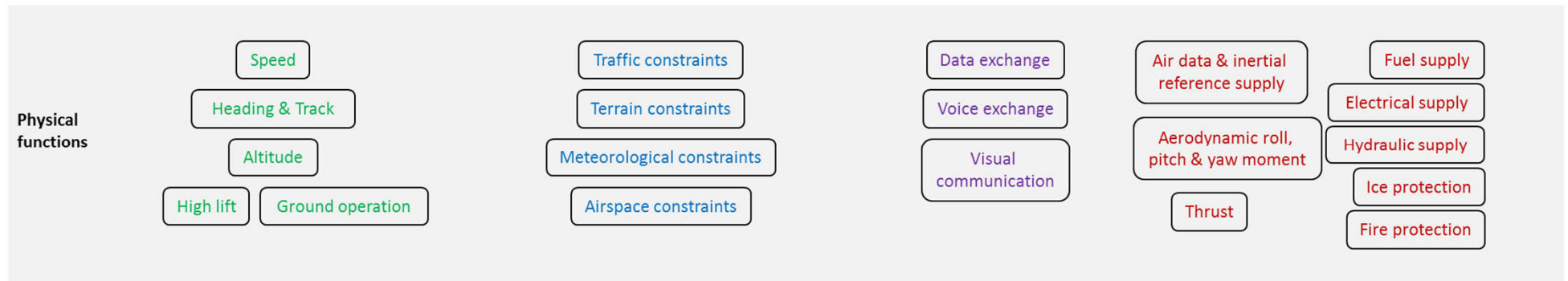
Visualization of functions as icons



Differentiation of system states by color



# Design Concept
















































































Visualization of functions as icons

Differentiation of system states by color

Visualization of function specific system parameters in a separate widget



## Design Concept Status Display

 U-Fly	UAS-1	UAS-2	UAS-3	UAS-4
Control				
				
				
				
				
				
Systems				
				
				
				
				
				
				
				
Protection				
				
				
				
				

➔ **System Control**

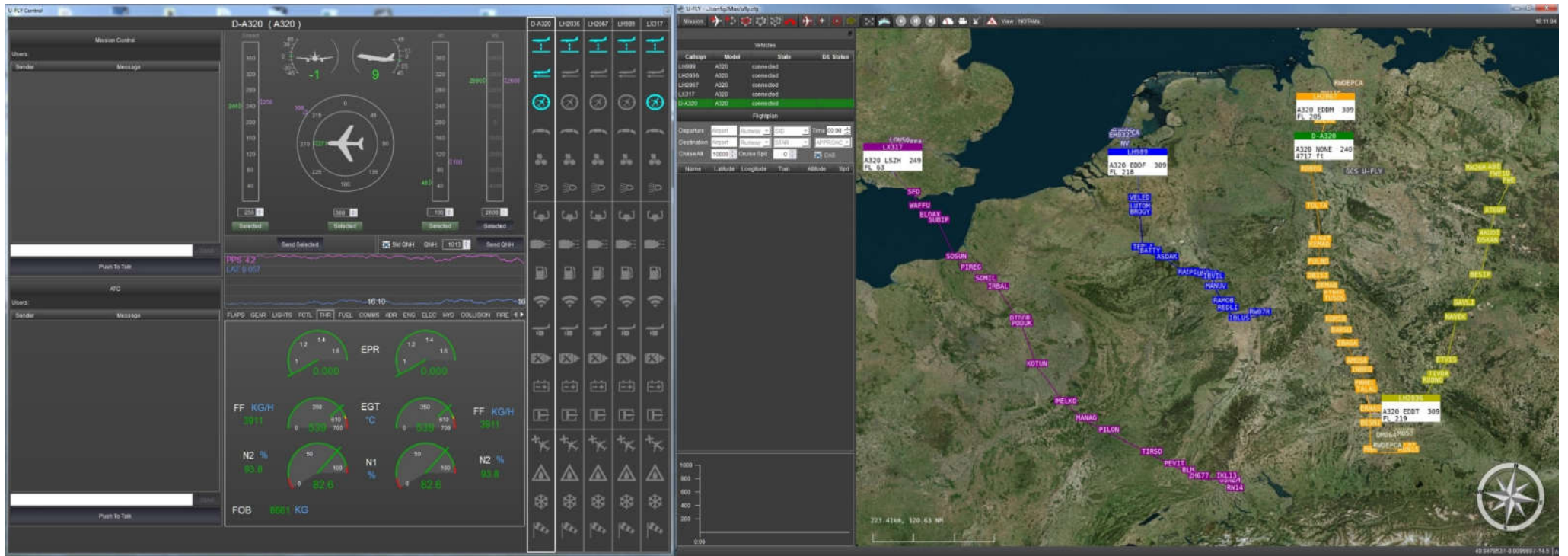
➔ **System Health**

➔ **System Protection**



# Human-Machine Interface

## DLR RPS Ufly



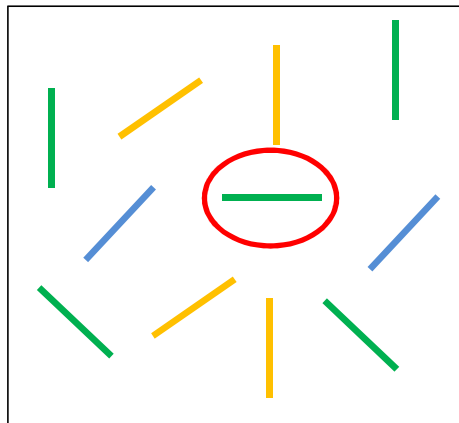


## Feature Based Interface Design

### Features (Treisman & Gelade, 1980)

#### Serial search (heterogeneous distractors):

Please find the unique object:



Linear increase in reaction time as a function of set size.

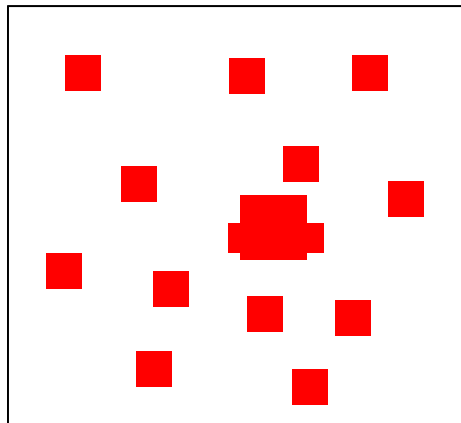


## Feature Based Interface Design

### Features (Treisman & Gelade, 1980)

**Parallel search (homogeneous distractors):**

Please find the unique object:





















Reaction time is independent of set size.



**Support parallel search!**







# Design Concept Icons

Function	Icon	Function	Icon
Altitude		Data & voice exchange – Radio communication	
Speed		Air data and inertial reference supply	
Heading & track		Thrust– Secondary engine parameters	
Aerodynamic lift & drag – Secondary flight controls		Electrical supply	
Ground operation – Landing gear		Hydraulic supply	
Visual communication – Lights		Traffic, terrain & airspace constraints	
Roll, pitch & yaw moment – Primary flight controls		Fire protection	
Thrust – Primary engine parameters		Ice protection	
Fuel supply		Meteorological constraints	



# Design Concept


## System States

System state	Color	Example
Normal		Altitude is within normal ranges
Transit		Aircraft is changing heading as expected
Caution		Potential hazard approaching (e.g. TCAS TA)
Warning		Engine parameter within critical ranges (e.g. oil temperature too high)



# Design Concept

## Status Display

 U-Fly	UAS-1	UAS-2	UAS-3	UAS-4
	